

LAMPIRAN



CODING YANG DI GUNAKAN

```
#include <SoftwareSerial.h>
#include <GSM_Shield.h>
#include <SPI.h>      //SPI.h must be included as DMD is written by SPI (the IDE complains
otherwise)
#include <DMDMega.h>    //
#include <TimerOne.h>  //
#include "SystemFont5x7.h"
#include "Arial_black_16.h"
#include <LiquidCrystal.h>
/*
The circuit:
* LCD RS pin to digital pin 12 => 22
* LCD Enable pin to digital pin 11 => 23
* LCD D4 pin to digital pin 5 => 24
* LCD D5 pin to digital pin 4 => 25
* LCD D6 pin to digital pin 3 => 26
* LCD D7 pin to digital pin 2 => 27
* LCD R/W pin to ground
* LCD VSS pin to ground
* LCD VCC pin to 5V
* 10K resistor:
* ends to +5V and ground
* wiper to LCD VO pin (pin 3)
*/

//Fire up the DMD library as dmd
#define DISPLAYS_ACROSS 1
#define DISPLAYS_DOWN 1
DMD dmd(DISPLAYS_ACROSS, DISPLAYS_DOWN);

boolean stringComplete = false; // whether the string is complete
boolean sms_valid = false;
boolean man_panel = false; // whether the string is complete
char newstr[256];
char newstr_lcd[256];

int sLength;

//*****
char number_incoming[20];
char number[]="+6285720061205"; //+6285720061205 Destination number
char text[]="[Auto Reply] SMS Diterima "; //SMS to send
byte type_sms=SMS_ALL; //Type of SMS
byte del_sms=1; //0: No deleting sms - 1: Deleting SMS
//*****

GSM gsm;
char sms_rx[122]; //Received text SMS
String teks_panel="";
```

```

String lcdpesan="";
//int inByte=0; //Number of byte received on serial port

//LiquidCrystal lcd(12, 11, 5, 4, 3, 2);
LiquidCrystal lcd(22, 23, 24, 25, 26, 27);

int call;
int error;

void ScanDMD()
{
  dmd.scanDisplayBySPI();
}

void setup()
{
  Serial.begin(9600);
  Serial.println("system startup");

  lcd.begin(16, 2);
  // Print a message to the LCD.
  lcd.setCursor(0,0);
  lcd.print(" System Startup");

  Timer1.initialize( 5000 ); //period in microseconds to call ScanDMD. Anything longer
than 5000 (5ms) and you can see flicker.
  Timer1.attachInterrupt( ScanDMD );

  lcd.setCursor(0,1);
  lcd.print(" ");
  lcd.print(" GSM Turn On.... ");

  gsm.TurnOn(9600); //module power on
  gsm.InitParam(PARAM_SET_1);//configure the module
  gsm.Echo(0); //enable AT echo

  dmd.clearScreen( true );

  lcd.clear();
}

void loop()
{
  char inSerial[5];
  int i=0;
  lcd.setCursor(0,0);
  lcd.print("==System Ready==n ");
  //

```

```
Check_Call(); //Check if there is an incoming call
Check_SMS(); //Check if there is SMS
```

```
//Check data serial com
if (Serial.available() > 0)
```

```
{
    while (Serial.available() > 0) {
        inSerial[i]=(Serial.read()); //read data
        i++;
    }
    inSerial[i]='\0';
    Check_Protocol(inSerial);
}
```

```
if (!man_panel) {
    teks_panel=sms_rx;
}
```

```
if (sms_valid)
{
    if (teks_panel=="")
        lcdpesan="Pesan : -";
    else
        lcdpesan="Pesan : "+teks_panel;
}
```

```
LCD_status(lcdpesan,true);
}
```

```
if (stringComplete)
{ if (!man_panel)
{
    teks_panel=sms_rx;
    Check_Protocol("s"); //auto reply
}
    sLength=teks_panel.length();
    teks_panel.toCharArray(newstr,sLength+1);
    Serial.print("Send To Display Panel \");
    Serial.print(teks_panel);
    Serial.println("");
    LCD_status("Send To Display",false);
    stringComplete = false;
    man_panel = false;
}
```

```
//dmd.selectFont(SystemFont5x7);
dmd.selectFont(Arial_Black_16);
dmd.clearScreen( true );
dmd.drawMarquee(newstr,sLength,(32*DISPLAYS_ACROSS)-1,0);
long start=millis();
long timer=start;
```

```

boolean ret=false;
while(!ret){
    if ((timer+30) < millis()) {
        ret=dmd.stepMarquee(-1,0);
        timer=millis();
    }
}
delay(1000);
}

```

```

void LCD_status(String inStr,boolean teksjalan)

```

```

{ if (teksjalan) {
    inStr=inStr+" ";
    sLength=inStr.length();
    inStr.toCharArray(newstr_lcd,sLength+1);
    runningText(16,newstr_lcd,1,200);
}
else
{
    lcd.setCursor(0,1);
    lcd.print(inStr);
}
return;
}

```

```

void runningText(int sizeColLcd, char message[], int row, int timerefresh){
    int textSize=strlen(message);
    char tempLcd[sizeColLcd];
    int tempPos =0;
    int iter;

    iter=textSize+sizeColLcd;

    for(int i=0; i<=iter; i++){
        if(i<sizeColLcd){
            memcpy(tempLcd, &message[0], i+1);
            lcd.setCursor(sizeColLcd-(i+1),row);
            lcd.print(tempLcd);
        }
        else {
            memcpy(tempLcd, &message[tempPos], sizeColLcd);
            lcd.setCursor(0,row);
            lcd.print(tempLcd);
            tempPos +=1;
        }

        delay(timerefresh);
    }
}

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```

    }
}

void Check_Protocol(String inStr)
{
    Serial.print("Command: ");
    Serial.println(inStr);

    Serial.println("Check_Protocol");

    switch (inStr[0])
    {
        case 't':
            stringComplete = true;
            Serial.println("Tes Manual Panel");
            teks_panel="Test Display OK";
            man_panel = true;
            break;

        case 'a': //Answer
            if (gsm.CallStatus()==CALL_INCOM_VOICE){
                gsm.PickUp();
                Serial.println("Answer");
            }
            else
            {
                Serial.println("No incoming call");
            }
            break;

        case 'c': // C //Call
            Serial.println(word(inStr.length()));
            if (inStr.length()==2) //To call variable 'number' comand c
            {
                Serial.print("Calling ");
                Serial.println(number);
                gsm.Call(number);
            }
            if (inStr.length()>2) //To call number in phone book position comand cx where x is
the SIM position
            {
                error=gsm.GetPhoneNumber(inStr[1],number);
                if (error!=0)
                {
                    Serial.print("Calling ");
                    Serial.println(number);
                    gsm.Call(number);
                }
                else
                {

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        Serial.print("No number in pos ");
        Serial.println(inStr[1]);
    }
}
break;

case 'h': //H //HangUp if there is an incoming call
if (gsm.CallStatus()!=CALL_NONE)
{
    Serial.println("Hang");
    gsm.HangUp();
}
else
{
    Serial.println("No incoming call");
}
break;

case 's': //S //Send SMS
Serial.print("Send SMS to ");
Serial.println(number);
error=gsm.SendSMS(number,number_incoming);
if (error==0) //Check status
{
    Serial.println("SMS ERROR \n");
}
else
{
    Serial.println("SMS OK \n");
}
break;

case 'p': //Read-Write Phone Book
if (inStr.length()==3)
{

    switch (inStr[1])
    {
        case 'd': //Delete number in specified position pd2
            error=gsm.DelPhoneNumber(inStr[2]);
            if (error!=0)
            {
                Serial.print("Phone number position ");
                Serial.print(inStr[2]);
                Serial.println(" deleted");
            }
            break;

        case 'g': //Read from Phone Book position
            pg2

```

```

error=gsm.GetPhoneNumber(inStr[2],number);
if (error!=0) //Find number in specified position
{
    Serial.print("Phone Book position ");
    Serial.print(inStr[2]);
    Serial.print(": ");
    Serial.println(number);
}
else //Not find number in specified position
{
    Serial.print("No Phone number in position ");
    Serial.println(inStr[2]);
}
break;
case 'w': //Write from Phone Book Position  pw2
error=gsm.WritePhoneNumber(inStr[2],number);
if (error!=0)
{
    Serial.print("Number ");
    Serial.print(number);
    Serial.print(" writed in Phone Book position ");
    Serial.println(inStr[2]);
}
else Serial.println("Writing error");
break;
}

}
break;

}

delay(1500);

return;
}

```

```

void Check_Call() //Check status call if this is available
{
    call=gsm.CallStatus();
    switch (call)
    {
        case CALL_NONE:
            Serial.println("Standby/no call");
            break;
        case CALL_INCOM_VOICE:
            gsm.CallStatusWithAuth(number_incoming,0,0);
            Serial.print("incoming voice call from ");
            Serial.println(number_incoming);

```

```

        break;
    case CALL_ACTIVE_VOICE:
        Serial.println("active voice call");
        break;
    case CALL_NO_RESPONSE:
        Serial.println("GSM no response");

        break;
    }
    return;
}

```

```

void Check_SMS() //Check if there is an sms 'type_sms'
{
    char pos_sms_rx; //Received SMS position
    String num_masuk="";
    String num_master="";
    pos_sms_rx=gsm.IsSMSPresent(type_sms);
    if (pos_sms_rx!=0)
    {
        //Read text/number/position of sms
        gsm.GetSMS(pos_sms_rx,number_incoming,sms_rx,120);
        Serial.print("Received SMS from ");
        Serial.print(number_incoming);
        Serial.print("(sim position: ");
        Serial.print(word(pos_sms_rx));
        Serial.println(")");
        Serial.println(sms_rx);
        num_masuk=number_incoming;
        num_master=number;
        LCD_status("SMS Masuk dari "+num_masuk,true);
        if (num_masuk!=num_master)
        { sms_valid=false;
          if (del_sms==1)
          { error=gsm.DeleteSMS(pos_sms_rx);
            if (error==0)
              Serial.println("SMS deleted numb asing");
            else
              Serial.println("SMS not deleted numb asing");
          }
          return;
        }
    }

    sms_valid=true;
    stringComplete = true;

    if (del_sms==1)
    { error=gsm.DeleteSMS(pos_sms_rx);
      if (error==0)

```

```
Serial.println("SMS deleted");  
else  
Serial.println("SMS not deleted");  
}  
}  
return;  
}
```



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